Problem Set III: Due Wednesday, October 23, 2013
Discussed in Problem Session on Tuesday, October 22, 2013
1.) A uniform bar of mass $M$ and length $2 \ell$ is suspended from one end by a spring of force constant $k$. The bar can swing freely in one vertical plane. The spring moves only vertically. Derive the Hamiltonian and the Hamiltonian equations of motion.
2.) Fetter and Walecka (FW): 6.1
3.) FW: 6.2
4.) FW: 6.4
5.) Derive Hamilton's equations directly from a modified version of the Principle of Least Action.
6.) Consider the Helmholtz equation for a sound wave in a medium with index of refraction $n(\underline{x})$.

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\nabla^{2} \psi+\frac{\omega^{2}}{c_{0}^{2}} n(\underline{x})^{2} \psi=0 .
$$

a.) For $n(\underline{x})^{2}=1+\delta(\underline{x})$, where $\delta \ll 1$, and assuming sound is beamed in the $\hat{z}$ direction, show the Helmholtz equation may be (approximately) re-written as:
$2 i k_{z} \frac{\partial \psi}{\partial z}+\nabla_{\perp}^{2} \psi+\frac{\omega^{2}}{c_{0}^{2}} \delta(\underline{x}) \psi=0$.
b.) Define $k_{r}$ here. The above equation is called the parabolic wave equation. Discuss
i.) the approximations inherent to this formulation.
ii.) the physical meaning of the different terms.
iii.) the restrictions on $\partial \psi / \partial z$, etc.
c.) Now, write $\psi=A(\underline{x}) e^{i \phi(\underline{x})}$. Use the parabolic wave equation to derive coupled equations for phase $\phi(\underline{x})$ and amplitude $A(\underline{x})$. Discuss the physical content of your result. Can you relate your result to that obtained using eikonal theory?
d.) Extra Credit:

What happens if $\delta_{(x)}$ is stochastic, so $\left\langle\delta_{(x)} \delta_{\left(x^{\prime}\right)}\right\rangle=\delta_{0}^{2} c\left(x-x^{\prime}\right)$. How would you calculate $\psi$ ?
7.) Consider an ocean with sound speed a function of depth, so that $c_{s}(z)$ is maximal at $z_{0}$, where $z$ is depth as measured from the surface. Using Fermat's Principle, determine the path that a ray takes to traverse a long distance $\ell$.

